LEVERS: A COMPUTER-ASSISTED INSTRUCTION

A THESIS

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CHAPTER I

Introduction

As in all other aspects of life, the country's largest industry, education, has been dramatically affected by the rapid technological advancement of the computer. Administrative functions such as class scheduling, record keeping, and payroll calculations have been assumed by computers in virtually all school districts. The potential of computer utilization in instructional enrichment has not yet been realized, however.

In the past, the relatively high cost of computers has made their use prohibitive in most classroom teaching environments. The present trend, however, shows computer costs declining to the point where, in some cases, it is now economically feasible to equip an entire school with adequate computer supplies to provide effective learning opportunities for all students. Indeed, Seidel and Rubin (29) predict that, soon, the cost of storing and transmitting information will be less than that required for print technology. Levien (20) agrees when he says that instructional computing costs will be reduced to "a few There is more to consider in cents per student hour." quality education than cost minimization however.

Ellis (10) warns that we will be tempted to modify current proven educational practices so that our teaching materials will be readily available for computerization. He adds that, as a consequence, we could develop inferior concepts of education.

Another area of concern among potential classroom computer users is the lack of good quality educational software. Jackson (17) has stated that "the figures that go around the [computer] industry are that only 3-5% of the educational programs that are available are worth looking at." He further explains that this void of good software can be attributed to the fact that the programs are either written by programmers who aren't educators or educators who aren't programmers. McGowan and Faust (22) concur when they that writing and testing new computer assisted state instruction (CAI) programs takes a considerable amount οf time and talent. An individual must be knowledgeable in the subject matter and must possess skills in instruction design, program writing and CAI.

The emergence and refinement of computer graphics has added a new dimension to CAI increasing potential applications greatly. Graphics, in addition to non-textual displays, can give the illusion of motion making the computer more adaptable in curricula where physical movement is the medium of study. In particular, aspects of physical

education, physical therapy, and occupational therapy instruction can be enhanced. Currently, usage of CAI is minimal in these movement-oriented disciplines when compared to others (33).

It is often difficult for students to fully comprehend some of the concepts relating to principles of movement when they are introduced through traditional teaching methods. Textbook illustrations, because of their static nature, are of limited value in improving understanding. The development of sound and effective CAI software in curricula involving physical activity would not only improve learning in those areas of study but would produce a cornerstone for further development of CAI in other instructional areas.

STATEMENT OF THE PROBLEM

This study entails the development of a computer program to aid in the teaching of a unit on levers and the concept of leverage. Through extensive use of interactive graphics, the effect of lever parameters on subsequent movement potential will be shown. Response-determined branching will be employed when appropriate and program include the recording of student capability will identification and response tracking in a separate file.

PURPOSE OF THE STUDY

The purpose of the investigation is to develop a computer program with graphics to be used as supplemental instruction in the study of the principles of leverage.

CHAPTER II

REVIEW OF RELATED LITERATURE

Introduction

The development of quality Computer Assisted Instruction is a very time consuming project. The following review of related literature was undertaken to ascertain the present state of the art in CAI software. In particular, the search will focus on 1) types of CAI, 2) historical CAI development, 3) microcomputers in education, 4) CAI effectiveness, and 5) CAI design techniques.

Types of CAI

Cleary, Mays, and Packham (6) define CAI as "the use of the computer as a sophisticated teaching machine which presents material to the student." They add that CAI can be presented in several types of modes:

- Drill and Practice the student is presented opportunities for application of acquired knowledge and allows the user to gain familiarity and competence with the material.
- Tutorial the student is presented with material for the first time. Acquisition of new facts and concepts is the main objective.

 Dialogue - the student can ask the computer questions and carry on fairly sophisticated conversation.

Drill and practice and tutorial modes of instruction appear to dominate present CAI program development. Doerr (8) states that drill and practice techniques are of most value in the educational environment. She elaborates by stating that a human teacher seems to be unnecessary when practice of previously learned material is the major goal.

Tutorial CAI, however, is designed to replace the teacher in presenting new facts. Doerr feels that tutorial CAI can be particularly effective in make-up work or in specialized individual instruction.

Historical CAI Development

Historically, computer software development has occurred at a slower rate than has computer hardware. This is particularly true for CAI. In the late 1950s the first uses of CAI were made almost exclusively by business and industry to train employees. Programming was complicated and tedious but IBM later produced an author language, Courseware 1, which enabled educators to program their ideas more directly (23). The first documented use of CAI in the schools occurred in 1959 when electric typewriters,

interfaced with an IBM 650 computer, presented instructional programs to New York elementary school children (3).

The noted success of IBM's experiment encouraged other major CAI development projects. In 1963 the Institute for Mathematical Studies in the Social Sciences at Stanford University produced a series of tutorial programs in mathematical logic. Additional drill and practice programs later supplemented Stanford's initial effort. Extensive program evaluation occurred during the following years. It was found that, when compared to a control group of students traditionally taught, CAI students performed better on SAT was true for both the tutorial and drill and This tests. practice CAIs. Stanford later instituted a Russian language program. It, too, met with similar success.

During the 1960s, the University of Illinois, working in conjunction with Control Data and the National Science Foundation developed and produced PLATO (Programmed Logic for Automated Teaching Operations). An interesting feature of PLATO is its touch sensitive screen panel which enables a user to touch an option or selection. This eliminates typing ability or, in the graphics mode, reading ability as prerequisites for utilization. Such programs can be used by very young children and by those who don't speak English. PLATO can readily be used in various instructional modes. Magidson (25) surveyed over 2000 students who had used PLATO

for an average of seven hours each and found that, overall, student attitudes were highly positive in their evaluation of PLATO. The only drawback often cited was difficulty with computer or terminal malfunctions. Today, Control Data Education Corporation offers learning and training centers in 50 cities in the United States. Several universities, secondary schools and even prisons also enjoy PLATO instructional opportunities. Presently, there are available volumes of CAI field-tested software in most curricular areas (32).

In 1972 Brigham Young University, funded by the MITRE corporation, began developing and researching an innovative idea called TICCIT (Time-shared, Interactive, Computer-Controlled, Information Television). The project was designed to combine computer and television technologies in presentation of CAI programs in Mathematics and in Instructional materials are presented on English. a television screen. Sequential displays are determined by the student, not the system. This is accomplished through a of "learner control" keys located on a keyboard pad interfaced with a computer. TICCIT is particularly designed for conceptual learning tasks. Evidence (15,26) suggests that, when the student has control over program pathways, learning is accomplished more quickly.

These early efforts in creating effective CAI have

resulted in programs that are still widely used in education, business, and industry. Often these CAI programs are used as a standard in the evaluation of new CAI software.

Microcomputers in Education

The recent marketing of relatively low-cost microcomputers has made the implementation of CAI accessible to most educational institutions. Microcomputers are "stand alone devices with binary data processing capability usually up to 54 thousand bytes." Presently prices vary from \$200 (13). Often other "peripheral" devices \$6000 to are necessary for educational computing (cathode ray tube, printer, disk drive, etc.). The National Science Foundation estimates that there are about 200,000 units in elementary and secondary schools and projected that, by 1985, one million microcomputers will be in service in these schools (13). Bork (4) estimated that from 1980 to 1985 the percentage of schools with CAI will increase from 54 percent to 74 percent.

This rapid introduction of microcomputers into the schools has manifested several problems. Some schools are purchasing many microcomputer and finding there is no one that can operate them. Teachers have found themselves lacking knowledge about computers and their possible

applications. Some (13) fear that teachers will resist computers much as they have earlier technologies.

Many microcomputers now offer capabilities to display Skyrme (30) states that "the human brain can graphics. quickly assimilate an image more easily than it can decipher text." Hammond (14) adds that software with graphics tends show rapid learning of a task that would otherwise be to difficult. Bork (4) states that graphics tend to separate the important from the trivial, and found student motivation higher with their use. When appropriately used, graphics can also demonstrate motion. This makes it particularly adaptable to motion oriented disciplines. Few applications are reported in subjects where movement or motion is the major medium.

CAI Effectiveness

of reduction, however, most Regardless cost institutions will not make this investment of time and money unless CAI has demonstrated cost-effective advantages over of instruction. Numerous modes traditional other investigations have been performed to compare learning effectiveness of CAI compared to that of other types of instruction. According to Splittgerber (31), the decision to implement CAI should focus on three questions:

1. What are the relative advantages over less

expensive traditional methods?

- 2. What is the amount of learning gain compared with other methods?
- 3. Have the identified teaching advantages reduced costs to a point that allows school districts to adopt CAI?

Magidson (24)found that CAI was superior to traditional methods in 45 percent and at least as effective in 55 percent of the surveyed studies. Student attitudes and learning efficiency also favored CAI. Lewellen (21) and Visonhaler and Bass (36) compared standardized test scores abstract reasoning and scholastic aptitude with those in traditionally taught. Results showed that students who used CAI performed better than those who did not. Tt was concluded that "students are able to learn more material in less time when the computer is properly utilized in the educational process" (35). Gleason (13) summarized CAI a 20 to 40 percent time research findings and reported saving in learning favoring CAI. Those studies surveyed also suggest that retention of learning is often better than that of conventional learning.

CAI Design Techniques

The development of one hour of CAI usually takes a programmer several hundred hours to prepare. In addition,

course objectives must be defined, program content verified and, upon completion, the program should be administered to representatives of the population for whom it was authored.

Gagne, Wager, and Rojas (11) warn that CAI authors must invest a considerable amount of advance planning before initiating actual software programming. Pre-programming procedures do not differ markedly from traditional preliminary planning for classroom instruction; the same principles of learning theory must be employed in both (13,24,27,28). Roblyer (28) offers several essential characteristics of good CAI software:

- Statement of objectives should be clearly stated and instructional rather than recreational.
- Statement of entry skills should define what preliminary information or abilities are necessary to benefit from the program.
- 3. Design of learning activities mode of instruction is defined (i.e. drill and practice), proper learning sequence is determined; each element of presentation is matched to the stated objectives.
- Design of tests On line tests (if appropriate) are written and validated.
- 5. Content integrity Evaluation of course content

for misspellings, grammatical errors, and misleading statements is performed.

 Design of presentation - All possible learning distractions (i.e., overuse of flashing text) are identified and eliminated.

Other programming considerations are: learner control, feedback, response format, graphics and animation. Each is described briefly below:

Learner control

The pattern and amount of information in a CAI can be controlled by the system or by the user (learner). Most (11,15,26) studies indicate that when the presentation is learner controlled, the student learns more quickly and has a more positive attitude towards the program.

Feedback

When a student makes a response he/she should be provided information relative to the appropriateness of that response. This is known as feedback. Hanson (15) found that system controlled feedback reduced learner anxiety levels. When feedback was learner controlled, the time to complete a high level reasoning task was reduced.

Response format

Sometimes it is desirable to accept responses expressed

in different ways. Care should be taken to avoid negative feedback for any possible response that is correct. The program must allow for all possible responses to ensure proper program flow.

Graphics and animation

Roblyer (28) states that graphics and animation should be used only when diagram or movement is critical for concept understanding. He suggested that overuse of graphics tends to distract learning. Caldwell (5), however, recommends that graphics and animation be used whenever they might spark an interest in the course content.

SUMMARY

A gleaning of the literature reveals that the early anticipated potential of computer assisted instruction has not yet been realized. The introduction of low cost microcomputers has made CAI accessible to most educational institutions. Unfortunately, CAI software development has not kept pace. Very few programs apply the principles of proven learning theories and, at the same time, make optimum use of the computer as the learning medium.

When quality CAI programs are used, research tends to show favorable results in learning compared to those found with traditional teaching methods. As the number of computer literate people rises, the quality of future CAI can be expected to improve dramatically. Sophisticated hardware and the development of new instructional programming languages will make CAI authoring easier and less time consuming.

CHAPTER III

PROGRAM DESIGN AND CONSTRUCTION

The purpose of this thesis was to develop a computer assisted instruction to supplement a student's introduction to the concepts of levers. Accomplishment of this task required two major phases: program design and program construction. An attempt was made, at all times, to follow CAI guidelines and recommendations as outlined in the literature review in Chapter II.

Program Design

Regardless of the method or type of knowledge transmission, there are several characteristics of optimally effective teaching. Theories of learning apply to the development of CAI just as they do in more traditional teacher planning.

The initial step in designing a course is to prepare a detailed description of the knowledges or skills that the student will possess upon successful course completion (22). These should always be available to the student and expressed in terms that will enable him to evaluate progress.

The following objectives were prepared for the CAI unit on levers. These objectives are available, on line, to the

student and also appear in a user manual (See Appendix B). Upon completion of all modules the student will:

- 1. Identify lever parts
- 2. Classify levers
- 3. Define lever terms
- 4. Perform lever calculations
- 5. Classify simple tools in terms of leverage

Course content and order of presentation were then established to optimally meet the objectives. Concurrently, a test was developed to assist in later program evaluation.

Course content was placed into one of three learning modules according to degree of difficulty and importance in understanding other related concepts. Module descriptions appear in Figure 1. Elaboration of each module's content appears in the user's manual in the Appendix. While the program allows for branching to any of these modules, the recommended learning sequence would be 1) definitions, 2) applications, and 3) quiz.



Figure III.-1: Program Branch Options

Upon completion of any module, the student has the option of branching to either of the other modules or of quitting. The learner therefore has some control over material presented.

Program flow is different for each module. In the definitions module, flow is linear; presenting and defining terms. Graphic displays are used to help define each term and demonstrate its relationship to other terms. Sample flow for the definitions module appears in Figure 2.



Figure III.-2: Program Flow for Definitions Module This tutorial mode has little flexibility and is basically system-controlled. The student must progress through the entire program but he can control the speed of presentation. The applications module was designed to provide opportunities to apply knowledge learned in the definitions module.

Program flow is somewhat more sophisticated. An



Figure III.-3: Program Control for Applications Module example is shown in Figure 3.

Again, graphics were used extensively to provide the questions and to enhance explanations.

The quiz module was constructed to be used for either drill and practice or for evaluation of student progress. Questions are presented in order of difficulty and incorrect answers receive a graphic explanation. Quiz questions assume the student has acquainted himself with the course content in the other two modules. Sample program control appears in Figure 4.

Upon completion of the quiz the student is provided with the number of incorrect answers and is given an



Figure III.-4: Program Flow for Quiz Module student information along with the questions missed and answers selected can be sent to a record keeping "filewriter" for later analysis by the instructor.

Program Construction

All programming was done in BASIC (Beginners All-purpose Symbolic Instructional Code). BASIC enjoys almost universal use in microcomputers (13). The programs were written for an APPLE II plus with 48K and an interfacing CRT (cathode ray tube). The APPLE is presently the most popular microcomputer in educational institutions (13) and has graphic capabilities superior to its

(13) and has graphic capabilities superior to its competitors.

Shape tables for high resolution graphic displays were prepared with the aid of special software authored by Robert Clardy and marketed by Synergistic Software. Text was formatted on coding forms designed specifically for the APPLE screen dimensions. A short introductory program was written to provide the user with the program title, author, and unit objectives. The shape table which is used in all three modules is loaded from this program. A "relocation" written to load each of the modules at an program was address lower than Apple's standard loading address. This was necessary to prevent the module from overwriting the high resolution screen.

Screen advancing is controlled by the student who can, therefore, take as much time as he needs. A message is flashed for any entry inconsistent with the type requested and the student is given another opportunity to respond.

A program user manual appears in Appendix B. The set of program listings can be found in Appendix A.

APPENDICES

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APPENDIX A

PROGRAM LISTINGS

INTRODUCTION PROGRAM

9 D\$ = CHR\$ (4): REM LOAD TITLE CHAR

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- 10 PRINT CHR\$ (4); "BLOAD LEVERS"
- 20 POKE 232,252
- 30 POKE 233,29
- 35 HOME
- 40 HGR
- 50 HCOLOR= 3
- 60 SCALE= 8
- 70 ROT = 0
- 80 X = 50
- 85 Y = 70
- 90 FOR I = 1 TO 3
- 95 IF I = 1 THEN GOSUB 300
- 96 IF I = 2 THEN GOSUB 600
- 97 IF I = 3 THEN GOSUB 300
- 100 DRAW I AT X,Y
- 105 GOSUB 700
- 110 X = X + 30
- 120 NEXT I
- 125 I = 2
- 126 GOSUB 600

130 DRAW 2 AT X,Y: REM USING "E" AGAIN?' 135 GOSUB 700 140 X = X + 30150 FOR I = 4 TO 5 155 IF I = 4 THEN GOSUB 300 160 IF I = 5 THEN GOSUB 600 166 DRAW I AT X,Y 167 GOSUB 700 168 X = X + 30170 NEXT I 180 FOR J = 1 TO 3000: NEXT J 190 TEXT 200 HOME INVERSE : FOR I = 2 TO 39: VTAB 2: HTAB I: PRINT " ": N 202 EXT 203 FOR I = 2 TO 23: VTAB I: HTAB 39: PRINT " ": NEXT FOR I = 39 TO 2 STEP - 1: VTAB 23: HTAB I: PRINT " ": 204 NEXT FOR I = 23 TO 2 STEP - 1: VTAB I: HTAB 2: PRINT " ": N 205 EXT 206 NORMAL 210 VTAB (7): HTAB (19): PRINT "BY" VTAB (10): HTAB (15): PRINT "JUDY TATE" 211 VTAB (13): HTAB (7): PRINT "TEXAS WOMAN'S UNIVERSITY" 212 213 VTAB (16): HTAB (18): PRINT "1982"?'

220 FOR J = 1 TO 4000: NEXT J

221 HOME : VTAB 3: HTAB 15: INVERSE : PRINT "OBJECTIVES": N ORMAL

222 VTAB 5: HTAB 1: PRINT "WHEN YOU FINISH THIS SET OF PROG RAMS YOU": VTAB 8: HTAB 1: PRINT "SHOULD BE ABLE TO:" 223 : VTAB 11: HTAB 5: PRINT "1. IDENTIFY LEVER PARTS" 224 VTAB 13: HTAB 5: PRINT "2. CLASSIFY LEVERS" VTAB 15: HTAB 5: PRINT "3. DEFINE LEVER TERMS" 225 226 VTAB 17: HTAB 5: PRINT "4. PERFORM LEVER CALCULATIONS" VTAB 19: HTAB 5: PRINT "5. CLASSIFY SIMPLE COMMON TOOLS 227 ": VTAB 21: HTAB 8: PRINT "IN TERMS OF LEVERAGE": VTAB 24: H TAB 7: INVERSE : PRINT "PRESS ANY KEY TO CONTINUE";: NORMAL : GET KEY\$ 228 HOME : VTAB 8: HTAB 7: PRINT "CHOOSE ONE OF THE FOLLOWI NG:" 230 VTAB 11: HTAB 7: PRINT "1. DEFINITIONS AND EXAMPLES" 235 VTAB 14: HTAB 7: PRINT "2. TEST" VTAB 17: HTAB 7: PRINT "3. QUIT" 240 244 INVERSE VTAB 20: HTAB 14: PRINT "CHOOSE 1,2, OR 3"; 245 246 NORMAL 250 GET CHOS: GOSUB 9700 IF PEEK (705) = 1 THEN POKE 705,0: GOTO 250 251 ON CHO GOTO 255,270,290 252 HOME : VTAB 12: HTAB 14: PRINT "PLEASE WAIT" 253

- 254 ON CHO GOTO 255,270290
- 255 PRINT " ": PRINT D\$; "RUN RELOCATE"
- 270 PRINT " ": PRINT D\$; "RUN MOVEMEM"
- 290 HOME : END
- 300 REM BRINGS LETTERS FROM BOTTOM OF
- 301 REM SCREEN
- 310 FOR Y = 140 TO 80 STEP 10
- 320 DRAW I AT X,Y
- 325 GOSUB 700
- 330 FOR J = 1 TO 100: NEXT J
- 340 XDRAW I AT X,Y
- 360 NEXT Y
- 370 RETURN
- 600 REM BRINGS LETTERS FROM TOP
- 601 REM OF SCREEN
- 610 FOR Y = 0 TO 70
- 620 DRAW I AT X,Y
- 625 GOSUB 700
- 630 FOR J = 1 TO 100: NEXT J
- 640 XDRAW I AT X,Y
- 650 Y = Y + 10
- 660 NEXT Y
- 670 RETURN ?'
- 700 REM PRODUCES CLICK WITH EACH LETTER DRAW
- 705 S = -16336

710 SOUND = PEEK (S) - PEEK (S) + PEEK (S) - PEEK (S) +
PEEK (S) - PEEK (S) + PEEK (S) + PEEK (S) - PEEK (S)
720 RETURN
9700 REM **CHECKS FOR VALIDITY
9701 REM ** OF ANSWER ***
9705 IF ASC (CHO\$) > 48 THEN IF ASC (CHO\$) < 53 THEN CHO
= ASC (CHO\$) - 48: RETURN
9710 POKE 705,1: VTAB 23: HTAB 4: PRINT "ENTER THE ";: INVE
RSE : PRINT "NUMBER";: NORMAL : PRINT " OF YOUR CHOICE ";
9715 FOR I = 1 TO 2000: NEXT
9750 RETURN</pre>

DEFINITIONS PROGRAM

- 12 REM BRANCH TO DEFINITIONS *
- 16 SP = 100
- 18 DIM T\$(40)
- 20 PRINT CHR\$ (4); "BLOAD NEWTAB, A\$8000"
- 25 POKE 232,0: POKE 233,128
- 26 SP = 255: POKE 700, 0
- 27 POKE 705,0: POKE 702,0
- 100 REM *** PAGE 1 ***
- 105 HOME :V = 8:H = 6:T\$ = "EVERY LEVER HAS THREE PARTS:"
- 110 GOSUB 5000
- 111 T = 2000: GOSUB 8000
- 115 V = 11:T\$ = "1. RESISTANCE (R)"
- 117 GOSUB 5000
- 118 T = 1000: GOSUB 8000
- 120 V = 14:T = "2. AXIS (A)"
- 121 GOSUB 5000
- 122 T = 1000: GOSUB 8000
- 125 V = 17:T\$ = "3. FORCE (F)"
- 126 GOSUB 5000
- 127 T = 2000: GOSUB 8000

128 V = 23:H = 15:T\$ = "PRESS ANY KEY TO CONTINUE": INVERSE : GOSUB 5000: NORMAL 130 GOSUB 9000 200 REM *** PAGE 2 *** 201 REM 202 HOME 205 V = 8:H = 2:T\$ = "THE ARRANGEMENT OF THESE THREE PARTS": GOSUB 5000 210 V = 11:H = 8:T\$ = "(RESISTANCE, AXIS, FORCE)": GOSUB 500 0 215 VTAB 14: HTAB 4: PRINT "WILL DETERMINE TO WHICH ";: INV ERSE : PRINT "CLASS";: NORMAL : PRINT " A" 220 V = 17:H = 13:T\$ = "LEVER BELONGS.": GOSUB 5000 230 GOSUB 9000 300 REM *** PAGE 3 *** 301 REM 303 HOME 305 V = 8:H = 4:T\$ = "THERE ARE THREE CLASSES OF LEVERS:": G OSUB 5000 310 T = 1000: GOSUB 8000 315 V = 11:H = 8:T\$ = "1. FIRST" 317 GOSUB 5000 318 T = 1000: GOSUB 8000 320 V = 14:T\$ = "2. SECOND": GOSUB 5000 325 T = 1000: GOSUB 8000

330 V = 17:T\$ = "3. THIRD": GOSUB 5000 335 T = 1500: GOSUB 8000 340 V = 21:H = 4:T\$ = "LET'S LOOK AT EACH ONE SEPARATELY.": GOSUB 5000 350 GOSUB 9000 360 TEXT : HOME 362 REM ** INSTRUCTION PAGE ** 365 HOME : V = 7:H = 5:T = "THE SEQUENCE OF LEVER COMPONENT S": GOSUB 5000 367 V = 10:H = 13:T\$ = "DETERMINES LEVER": GOSUB 5000 369 V = 13:H = 17:T\$ = "CLASS.": GOSUB 5000 370 GOSUB 9000: HOME 371 V = 8:H = 6:T\$ = "ON THE FOLLOWING DIAGRAM MOVE": GOSUB 5000 373 V = 12:H = 10:T\$ = "THE AXIS AND WATCH THE": GOSUB 5000 375 V = 16:H = 6:T\$ = "LEVER CLASSIFICATION CHANGE.": GOSUB 5000: GOSUB 9000 376 HOME 377 V = 10:H = 3:T\$ = "TO MOVE THE AXIS TO THE LEFT TYPE 'L' ": GOSUB 5000 379 V = 13:TS = "TO MOVE THE AXIS TO THE RIGHT TYPE 'R'": GO SUB 5000 381 V = 16:TS = "TO COME BACK TO THIS PAGE TYPE 'I'": GOSUB 5000 385 GOSUB 9000

400 REM *** DISPLAY LEVER SYSTEM *** 401 GOSUB 6100 460 V = 22:H = 10:T\$ = "A FIRST CLASS LEVER": GOSUB 5000 470 V = 24:H = 1:TS = "THE AXIS IS BETWEEN FORCE AND RESISTA NCE": GOSUB 5000 480 T = 3000: GOSUB 8000: HOME 500 X = 125: GOSUB 6200 IF AX = "I" THEN TEXT : GOTO 376 505 REM *** PAGE 6 *** 600 601 REM 503 TEXT : HOME 605 V = 8:H = 7:T\$ = "LEVERS ENABLE A USER TO GAIN": GOSUB 5 000 VTAB 11: HTAB 16: INVERSE : PRINT "EITHER": NORMAL 610 615 VTAB 15: HTAB 13: PRINT "FORCE ";: INVERSE : PRINT "OR" ;: NORMAL : PRINT " SPEED" 620 V = 19:H = 18:T\$ = "BUT...." 621 GOSUB 5000 625 GOSUB 9000 700 REM ** PAGE 7 ** 701 REM 705 HOME :V = 11:H = 13:T\$ = "BEFORE CONTINUING": GOSUB 500 0 710 V = 14:H = 6:T\$ = "WE NEED TO LEARN SOME NEW TERMS:": GO SUB 5000

711 GOSUB 9000 712 HOME 715 V = 8:H = 6:T\$ = "FORCE ARM - PERPENDICULAR DISTANCE": G OSUB 5000 $720 \text{ V} = 10:\text{H} = 18:\text{T}^{\circ} = "\text{BETWEEN THE AXIS AND"}: GOSUB 5000$ 725 V = 12:TS = "THE POINT OF APPLICA-": GOSUB 5000 728 V = 14:T\$ = "TION OF FORCE.": GOSUB 5000 735 V = 22:H = 13:T\$ = "FORCE ARM = FA": GOSUB 5000 740 GOSUB 9000 800 REM ** GRAPHICS (FA) ** 801 REM 805 GOSUB 6100 808 X = 125:Y = 158810 GOSUB 6500 815 GOSUB 9000 820 REM *** PAGE 7B *** 825 TEXT : HOME :V = 7:H = 6:T\$ = "RESISTANCE ARM - PERPEND ICULAR": GOSUB 5000 830 V = 9:H = 18:T\$ = "DISTANCE BETWEEN THE": GOSUB 5000 835 V = 11:TS = "AXIS AND THE POINT OF": GOSUB 5000 840 V = 13:T\$ = "RESISTANCE. (RA)": GOSUB 5000 845 V = 22:H = 10:TS = "RESISTANCE ARM = RA": GOSUB 5000845 GOSUB 9000 847 GOSUB 6100 848 X = 125: DRAW 5 AT X,80:X = 122
849 POKE 705, 1:Z = 92850 GOSUB 6600 855 GOSUB 9000 860 REM ** PAGE 10 *** 861 REM 865 TEXT : HOME : SPEED= 255 870 VTAB 6: HTAB 3: PRINT "A ";: INVERSE : PRINT "SECOND";: NORMAL : PRINT " CLASS LEVER ALWAYS HAS A" 875 V = 12:H = 7:T\$ = "LONGER FORCE ARM AND FAVORS": GOSUB 5 000 880 V = 18:H = 17: INVERSE : T\$ = "FORCE": GOSUB 5000: NORMAL 885 GOSUB 9000 887 X = 71: POKE 700, 1890 GOSUB 6100 892 X = 71: DRAW 5 AT X,80893 GOSUB 6000: VTAB 21: HTAB 1: PRINT "FORCE ARM IS LONGER THAN RESISTANCE ARM" 894 GOSUB 7200:Y = 158895 X = 71: GOSUB 6500898 T = 300: GOSUB 8000 900 Y = 92:X = 71901 GOSUB 6900 905 GOSUB 9000 950 REM *** PAGE 10B ***

951 REM 952 TEXT : HOME 955 VTAB 6: HTAB 4: PRINT "A ";: INVERSE : PRINT "THIRD";: NORMAL :60 VT\$ = "LONGER RESISTANCE ARM AND FAVORS": GOSUB 5 000 965 INVERSE :V = 18:H = 17:T\$ = "SPEED": GOSUB 5000: NORMAL 970 GOSUB 9000 972 GOSUB 6100: DRAW 5 AT 185,80 975 GOSUB 6000: VTAB 21: HTAB 1: PRINT "RESISTANCE ARM IS L ONGER THAN FORCE ARM" 976 X = 185: GOSUB 7200 977 Y = 92978 Z = 161 979 POKE 705,0: GOSUB 6600 980 GOSUB 9000 985 X = 183:Y = 92:Z = 161987 GOSUB 6930 989 GOSUB 9000 1000 REM ** PAGE 10B ** 1001 REM 1005 TEXT : HOME 1010 VTAB 4: HTAB 6: PRINT "A ";: INVERSE : PRINT "FIRST";: NORMAL : PRINT " CLASS LEVER MAY HAVE" 1015 VTAB 8: HTAB 17: INVERSE : PRINT "EITHER": NORMAL

1020 V = 12:H = 11:T = "A LONGER FORCE ARM": GOSUB 5000 1025 VTAB 16: HTAB 19: INVERSE : PRINT "OR": NORMAL 1030 V = 20:H = 8:T\$ = "A LONGER RESISTANCE ARM": GOSUB 5000 1032 GOSUB 9000 1035 HOME : V = 5: H = 4: T\$ = "WHENEVER WE DIVIDE THE LENGTH OF" 1037 GOSUB 5000 1040 V = 8:H = 10:T = "THE FORCE ARM BY THE": GOSUB 5000 $1045 \text{ V} = 11:\text{H} = 7:\text{T}^{\circ} = \text{"LENGTH OF THE RESISTANCE ARM": GOSUB}$ 5000 1050 V = 14:H = 14:T\$ = "WE GET THE": GOSUB 5000 1055 V = 17:H = 10:T\$ = "MECHANICAL ADVANTAGE": INVERSE : GO SUB 5000: NORMAL 1060 V = 20:H = 17:T\$ = "SO...": GOSUB 5000 1062 GOSUB 9000: HOME 1065 V = 10:H = 22:T = "FA": GOSUB 5000 1070 V = 11:H = 16:T = "MA = ---": GOSUB 5000 1075 V = 12:H = 22:T = "RA": GOSUB 5000 1080 GOSUB 9000 TEXT : HOME :V = 5:H = 8:T\$ = "ON THE FOLLOWING DIAGRA 2060 M": GOSUB 5000 2065 V = 8:H = 13:T\$ = "MOVE THE AXIS": GOSUB 5000 2070 V = 11:H = 7:T\$ = "AND NOTICE THE CHANGES IN:": GOSUB 5 000 2075 V = 14:H = 15:T\$ = "1. CLASS"

2076 GOSUB 5000 2080 V = 16:T\$ = "2. FORCE ARM" 2081 GOSUB 5000 2085 V = 18:T\$ = "3. RESISTANCE ARM" 2086 GOSUB 5000 2090 V = 20:T\$ = "4. MECHANICAL ADVANTAGE" 2091 GOSUB 5000 2095 GOSUB 9000 3000 POKE 700,0: GOSUB 6100: GOSUB 7100 4000 TEXT : HOME :V = 10:H = 4:T\$ = "IT IS IMPORTANT TO UND ERSTAND THE": GOSUB 5000 4005 V = 14:H = 12:T\$ = "PRECEEDING TERMS.": GOSUB 5000: GOS UB 9000 4008 HOME 4015 V = 9:H = 6:T\$ = "FOR NOW, WOULD YOU LIKE TO:": GOSUB 5 000 4020 V = 12:H = 12:T\$ = "1. TAKE A QUIZ": GOSUB 5000 4030 V = 15:T\$ = "2. QUIT": GOSUB 5000 4040 V = 23:H = 4:T\$ = "ENTER THE NUMBER OF YOUR CHOICE": GO SUB 5000 4050 GET CHO\$: GOSUB 9700: NORMAL 4051 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 4050 IF CHO = 1 THEN HOME :: VTAB 12: HTAB 15: PRINT "PLEA 4055 SE WAIT": PRINT CHR\$ (4)"RUN MOVEMEM" 4070 HOME

4999	END
5000	REM **** THIS SUBROUTINE PRINTS
5001	REM **** LINES ONE AT A TIME ****
5002	REM
5005	SPEED= 255
5010	HTAB H
5015	FOR I = 1 TO LEN (T\$)
5017	VTAB V
5020	PRINT MID\$ (T\$,I,1);
5030	NEXT I
5050	RETURN
6000	REM *** SETS LABEL WINDOW ***
6001	REM
6005	VTAB 24: HTAB 12
5010	CALL - 958
6050	RETURN
6100	REM *** DRAWS LEVER SYSTEM ***
5101	REM
6105	HGR : HCOLOR= 3: ROT= 0: SCALE= 1
6110	DRAW 1 AT 100,80
6115	DRAW 2 AT 85,77
6120	DRAW 3 AT 149,84
6125	DRAW 4 AT 146,77
6127	IF PEEK (700) = 1 THEN RETURN
6130	DRAW 5 AT 125,80

.

6150 RETURN 6200 REM *** MOVES AXIS *** 6201 REM 6202 HOME 6203 V = 22:H = 126204 T = "FIRST CLASS LEVER ":G\$ = T\$ 6205 INVERSE : GOSUB 5000: NORMAL : GOSUB 6400 6207 X = 125: REM SETS AXIS AT ORIGIN 6210 GET AX\$ 6214 IF AX\$ = "C" THEN RETURN 6215 IF AX\$ = "L" THEN GOTO 6260 6220 IF AX\$ = "R" THEN GOTO 6280 6225 IF AX\$ = "I" THEN RETURN 6230 VTAB 23: HTAB 5: INVERSE : PRINT "ENTER ONLY L,R OR C" : PRINT "": NORMAL : GOTO 6210 6260 XDRAW 5 AT X,80:X = X - 5: GOSUB 7400: DRAW 5 AT X,80 6265 GOSUB 6300 6270 IF X < 90 THEN G\$ = "SECOND CLASS LEVER": POKE 702,1: GOTO 6290 6271 IF X < 165 THEN G\$ = "FIRST CLASS LEVER " 6272 GOTO 6290 6280 XDRAW 5 AT X,80:X = X + 5: GOSUB 7400: DRAW 5 AT X,80: GOSUB 6300 6281 IF X > 160 THEN G\$ = "THIRD CLASS LEVER": POKE 702,1: GOTO 6:TS = GS: INVERSE :V = 22: GOSUB 5000: NORMAL

6291 V = 226295 GOTO 6210 6299 RETURN 6300 REM ** PRODUCES SOUND WHEN 6301 REM ** CLASS CHANGES ** 6302 REM 6310 S = -163366315 SOUND = PEEK(S) - PEEK(S) + PEEK(S) - PEEK(S) +PEEK (S) - PEEK (S) 6330 RETURN 6400 REM ** PRINTS DISPLAY INSTRUCTIONS REM ** FOR AXIS MOVEMENT ** 6401 VTAB 21: HTAB 2: PRINT "L=LEFT R=RIGHT C=CONTI 6405 NUE" VTAB 23: HTAB POS (1) + 1 6415 6420 VTAB 23: HTAB 30 6450 RETURN REM ** FORCE ARM *** 6500 6502 ROT = 06505 DRAW 7 AT X,90 6510 GOSUB 6300: REM ** SOUND ** 6515 FOR I = 1 TO 200: NEXT 6520 X = X + 36530 IF X = Y THEN ROT= 16: DRAW 7 AT X + 3,90: ROT= 0:P = 8:Q = 9: GOSUB 7300: RETURN

6545 GOTO 6505 6550 RETURN 6600 REM ** RESISTANCE ARM ** DRAW 7 AT X - 3,90: GOSUB 6300 6610 6612 ROT= 0 6615 T = 200: GOSUB 8000 6625 X = X - 26626 P = 8:Q = 9: IF PEEK (705) = 1 THEN P = 106630 IF X = Z THEN ROT= 16: DRAW 7 AT X,90: ROT= 0: GOSUB 7300: RETURN 6635 GOTO 6610 6640 POKE 705,0 6650 RETURN 6700 REM *** MOVES AXIS *** 6701 REM GET AXS 6705 6710 XDRAW 5 AT X,80 IF AX\$ = "C" THEN RETURN 6715 6720 IF AX\$ = "L" THEN X = X - 5: GOTO 6740 6730 IF AX\$ = "R" THEN X = X + 5: GOTO 6740 VTAB 21: HTAB 1 PRINT " 6735 ": VTAB 21: HTAB 11 PRINT "ENTER ONLY L,R, OR C" DRAW 5 AT X,80: GOSUB 6300 6740 6745 GOSUB 6800 6750 RETURN

6800 REM ** CALCULATES AND PRINTS FA, * * 6801 REM RA, AND MA ** 6805 FA = ABS (160 - X): RA = ABS (X - 90)6815 CLS = "1ST"6820 IF X < 90 THEN CLS = "2ND" 6825 IF X > 164 THEN CL\$ = "3RD" 6826 IF RA = 0 THEN RA = 1 6828 IF FA = 0 THEN FA = 1 5829 MA = FA / RA6830 MA = (INT (MA * 100)) / 100 6832 INVERSE VTAB 21: HTAB 21: PRINT CL\$ 6835 6836 VTAB 22: HTAB 8: PRINT FA 6837 VTAB 22: HTAB 22: PRINT RA 6838 VTAB 22: HTAB 35: PRINT MA 6840 NORMAL 6850 RETURN REM ** MAKES DASHED LINES ** 5900 6901 GOSUB 9000 DRAW 7 AT X,100 6902 ROT = 06903 6905 DRAW 7 AT X - 3,100 6908 GOSUB 6300 6909 T = 300: GOSUB 80006910 IF X = Y - 7 THEN ROT= 16: DRAW 7 AT X + 3,100: ROT=

0:P = 10:Q = 9: GOSUB 7300: RETURN

6912 IF X = Y - 7 THEN DRAW 7 AT X + 3,100:P = 10:Q = 9: G OSUB 7300: RETURN 6916 X = X + 76920 GOTO 6905 6925 RETURN 6930 REM **MAKES DASHED LINES ** REM ** GOING LEFT ** 6931 6938 DRAW 7 AT X,100 6940 ROT = 06950 DRAW 7 AT X - 1,100 6958 GOSUB 6300 6960 FOR I = 1 TO 200: NEXT 6965 IF X = Y - 7 THEN ROT= 16: DRAW 7 AT X + 1,100: ROT= 0:P = 10:Q = 9: GOSUB 7300: RETURN 6970 X = X - 76975 GOTO 6950 6980 RETURN 7000 REM ** PRINTS LABELS ** 7005 GOSUB 6000 7010 V = 21:H = 87020 GOSUB 5000 7025 RETURN 7100 REM DRAWS LEVER SYSTEM

7105 X = 125

7106 GOSUB 6000: VTAB 21: HTAB 15: PRINT "CLASS " 7108 VTAB 22: HTAB 1: PRINT " FA = RA =M п A = 7109 GOSUB 6800: VTAB 22: HTAB 39: GET AX\$ 7110 GET AX\$: GOSUB 6300: GOSUB 7500 7111 IF AX\$ = "C" THEN RETURN 7112 IF AXS = "L" THEN XDRAW 5 AT X,80:X = X - 5: GOSUB 74 00 7114 IF AX\$ = "R" THEN XDRAW 5 AT X,80:X = X + 5: GOSUB 74 00 7115 IF PEEK (709) = 0 THEN VTAB 23: HTAB 2: PRINT "ENTER ONLY 'L', 'R', OR 'C'" 7117 POKE 709,0: DRAW 5 AT X,80 7118 GOSUB 6800 7120 GOTO 7110 7125 RETURN 7200 REM *** PRINTS CLASS LABELS *** 7205 CL\$ = "1ST CLASS LEVER" IF X < 90 THEN CLS = "2ND CLASS LEVER" 7210 7215 IF X > 165 THEN CLS = "3RD CLASS LEVER" 7223 INVERSE 7225 VTAB 23: HTAB 12: PRINT CL\$ 7230 NORMAL 7250 RETURN 7300 REM PRINTS RA AND FA *****

- 7305 DRAW P AT X 4,110
- 7310 DRAW Q AT X + 4,110
- 7350 RETURN
- 7400 REM ** COMPARISON FOR LIMITS
- 7405 IF X > 180 THEN X = 180
- 7410 IF X < 70 THEN X = 70
- 7412 POKE 709,1
- 7415 RETURN
- 7500 REM CLEARS LINE FOR 6800
- 7510 INVERSE : VTAB 22: HTAB 8: PRINT "
- 7515 VTAB 22: HTAB 22: PRINT " "
- 7520 VTAB 22: HTAB 35: PRINT "
- 7525 NORMAL
- 7530 RETURN
- 7700 REM ** DRAWS ARROW **
- 7705 ROT= 32
- 7710 IF PEEK (702) < > 0 THEN ROT= 0
- 7712 XDRAW 6 AT 180,80
- 7715 DRAW 6 AT 180,80
- 7720 ROT= 0
- 7725 RETURN
- 8000 REM **** DELAYS PRINTING
- 8005 FOR I = 1 TO T: NEXT
- 8050 RETURN
- 9000 REM *** WAITS FOR INPUT

- 9001 REM
- 9005 VTAB V: HTAB POS (2) + 1
- 9010 FLASH
- 9012 POKE 16368,0
- 9015 GET KEY\$
- 9020 NORMAL
- 9050 RETURN
- 9700 REM ** TEST FOR VALIDITY **
- 9701 REM *********************
- 9705 IF ASC (CHO\$) > 48 THEN IF ASC (CHO\$) < 53 THEN CHO
- = ASC (CHO) 48: RETURN
- 9710 POKE 709,1
- 9715 VTAB 23: HTAB 4: INVERSE : PRINT "ENTER THE NUMBER OF YOUR CHOICE"
- 9750 RETURN

APPLICATIONS PROGRAM

6 7 REM BRANCH TO APPLICATIONS 8 9 DIM T\$(40) 10 PRINT CHR\$ (4); "BLOAD NEWTAB, A\$8000" 15 POKE 232,0: POKE 233,128 18 F = 10:R = 60POKE 300,0: POKE 700,0: POKE 701,0 19 20 SP = 255HOME : V = 9:H = 7:T\$ = "LET'S SEE HOW WELL YOU CAN": GOS 25 UB 5000 30 V = 12:H = 10:T\$ = "APPLY YOUR KNOWLEDGE": GOSUB 5000 35 V = 15:H = 15:T\$ = "OF LEVERS.": GOSUB 5000 40 GOSUB 9000 100 REM PAGE 2 105 HOME : V = 6:T = "TO MAKE A LEVER BALANCE, THE AMOUNT": H = 2: GOSUB 5000110 V = 9:H = 2:T\$ = "OF RESISTANCE TIMES THE LENGTH OF THE" : GOSUB 5000 115 V = 12:T\$ = "RA MUST EQUAL THE AMOUNT OF THE ":H = 4: GO SUB 5000 120 V = 15:T\$ = "FORCE TIMES FA.":H = 12: GOSUB 5000

125 V = 18:H = 18:T\$ = "SO...": GOSUB 5000 130 GOSUB 9000 200 REM PAGE 3 205 GOSUB 4000 210 X = 125: GOSUB 6100 215 GOSUB 6200 220 IF PEEK (300) = 1 THEN GOTO 210 300 REM ** PAGE 4 ** 302 REM ********* 305 HOME :V = 8:H = 5:T\$ = "OF COURSE, LEVERS ARE USED FOR" : GOSUB 5000 310 V = 11:H = 6:T\$ = "PURPOSES OTHER THAN BALANCE.": GOSUB 5000 315 VTAB 14: HTAB 5: PRINT "MANY ";: INVERSE : PRINT "TOOLS ";: NORMAL : PRINT " APPLY THE PRINCIPLES" 320 V = 17:H = 15:T\$ = "OF LEVERAGE": GOSUB 5000: GOSUB 9000 REM ** PAGE 5 ** 400 402 REM ********* 405 HOME : V = 5: H = 5: T\$ = "FOR INSTANCE, A WHEELBARROW CAN ": GOSUB 5000 410 V = 8:T\$ = "BE CLASSIFIED AS A LEVER WITH": GOSUB 5000 415 V = 11:T\$ = "THE FOLLOWING PARTS:": GOSUB 5000 420 V = 14:T\$ = "1. AXIS = WHEEL AXLE": GOSUB 5000 425 V = 16:T\$ = "2. R = WEIGHT OF LOAD": GOSUB 5000 430 V = 18:T = "3. F = LIFTING FORCE AT": GOSUB 5000

435 V = 20:H = 15:T\$ = "HANDLES": GOSUB 5000 440 GOSUB 9000 500 REM ** PAGE 6 ** 502 REM ********** 505 HOME :V = 8:H = 4:T\$ = "LOOK AT THE FOLLOWING WHEELBARR OW": GOSUB 5000 510 V = 11:H = 9:T = "AND TELL ME WHAT LEVER": GOSUB 5000 515 V = 14:H = 10:T = "CLASSIFICATION IT IS.": GOSUB 5000 520 GOSUB 9000 522 X = 100: Y = 110: X2 = 113: Y2 = 87: X3 = 115: Y3 = 72: R = 64525 GOSUB 9500: GET ANS\$: GOSUB 9700 IF PEEK (705) = 1 THEN POKE 705,0: GOTO 525 526 528 TEXT : HOME 530 IF ANS = 2 THEN V = 11:H = 2:T = "VERY GOOD, A WHEELBA RROW IS AN EXAMPLE": GOSUB 5000:V = 14:H = 9:T = "OF A SECO ND CLASS LEVER.": GOSUB 5000: GOSUB 9000: GOTO 540 535 V = 11:H = 8:T\$ = "WRONG! A WHEELBARROW IS A": GOSUB 500 0 537 V = 14:H = 10:T = "SECOND CLASS LEVER": GOSUB 5000: GOS UB 9000 545 GOSUB 9500 560 HOME : VTAB 23: HTAB 12: INVERSE : PRINT "2ND CLASS LEV ER": NORMAL 570 GOSUB 9000 600 REM **START SCISSORS**

601 REM ************** 605 TEXT : HOME 610 V = 8:T = "ANOTHER TOOL THAT IS A LEVER": H = 7: GOSUB 5 000 615 V = 11:H = 10:T\$ = "IS A PAIR OF SCISSORS": GOSUB 5000 620 GOSUB 9000 700 REM ** PAGE 2 OF SCISSORS ** 701 705 HOME 710 V = 9:H = 4:T\$ = "WHAT CLASS OF LEVER DO THINK": GOSUB 5 000 715 V = 12:H = 9:T\$ = "A PAIR OF SCISSORS IS?": GOSUB 5000 720 GET ANSS: GOSUB 9700 721 IF PEEK (705) = 1 THEN POKE 705,0: GOTO 720 722 TEXT : HOME IF ANS = 1 THEN GOTO 765725 730 V = 11:H = 7:T\$ = "NO, A PAIR OF SCISSORS IS A": GOSUB 5 000 735 V = 14:H = 12:T\$ = "FIRST CLASS LEVER": GOSUB 5000 740 GOSUB 9000 745 HOME 750 V = 8:H = 2:T\$ = "LOOK AT OUR SCISSORS. WHEN THEY CUT": GOSUB 5000 755 V = 11:H = 1:TS = "PAPER THE RESISTANCE IS THE PAPER AND ": GOSUB 5000

758 V = 14:T\$ = "THE AXIS IS THE CONTACT POINT OF THE TWO":H = 1: GOSUB 5000 759 V = 17:TS = "PARTS AND FORCE IS AT THE HANDLES.":H = 2: GOSUB 5000 760 GOSUB 9000: GOTO 785 765 HOME 770 V = 12:T = "RIGHT! A PAIR OF SCISSCORS IS A 1ST":H = 2: GOSUB 5000 772 V = 15:H = 15:T\$ = "CLASS LEVER": GOSUB 5000 775 GOSUB 9000 785 X = 144: GOSUB 9400 3999 END 4000 HOME : V = 10: H = 13: T\$ = "BALANCE MEANS": GOSUB 5000 4005 V = 13:H = 12:T\$ = "F X FA = R X RA": GOSUB 5000 4010 GOSUB 9000 4020 RETURN 5000 REM **** THIS SUBROUTINE PRINTS 5001 REM **** LINES ONE AT A TIME **** 5002 REM SPEED= 255 5005 5010 HTAB H 5015 FOR I = 1 TO LEN (T\$) 5017 VTAB V PRINT MIDS (T\$,I,1); 5020 5030 NEXT I

5050 RETURN 6000 REM *** SETS LABEL WINDOW *** 6001 REM 6005 VTAB 24: HTAB 12 6010 CALL - 958 6050 RETURN 6100 REM *** DRAWS LEVER SYSTEM *** 6101 REM 6105 HGR : HCOLOR= 3: ROT= 0: SCALE= 1 6110 DRAW 1 AT 100,80 6115 DRAW 2 AT 85,77 6120 DRAW 3 AT 149,84 6125 DRAW 4 AT 146,77 6130 DRAW 5 AT X,80 6150 RETURN 6200 REM BALANCE LEVER 6205 VTAB 21: HTAB 1: PRINT "FORCE = ";: INVERSE : PRINT F; : NORMAL : PRINT " RESISTANCE = ";: INVERSE : PRINT R: NORMAL 6207 IF PEEK (300) = 2 THEN GOTO 6215 11 6208 VTAB 23: HTAB 1: PRINT " 6210 VTAB 23: HTAB 5: INVERSE : PRINT "TYPE 'B' WHEN LEVER WILL BALANCE": NORMAL 6215 GOSUB 9100 6217 IF PEEK (300) = 2 THEN RETURN

- 6220 VTAB 23: HTAB 39: GET AX\$
- 6225 IF AX\$ < > "R" THEN IF AX\$ < > "L" THEN GOTO 6230
- 6226 XDRAW 5 AT X,80
- 6230 IF AX\$ = "B" THEN GOSUB 9200: RETURN
- 6235 IF AXS = "L" THEN X = X 5: GOTO 6240
- 6237 IF AX\$ = "R" THEN X = X + 5: GOTO 6240
- 6238 VTAB 23: HTAB 1: PRINT "

": VTAB 23: HTAB 1: PRINT "ENTER ONLY L, R, OR B": FOR

- I = 1 TO 2000: NEXT
- 6239 GOTO 6205
- 6240 GOSUB 7400
- 6245 DRAW 5 AT X,80
- 6250 GOSUB 6300
- 6255 GOSUB 9100
- 6260 GOTO 6220
- 6270 RETURN
- 6300 REM ** PRODUCES SOUND WHEN
- 6301 REM ** CLASS CHANGES **
- 6302 REM
- 6310 S = -16336
- 6315 SOUND = PEEK(S) PEEK(S) + PEEK(S) PEEK(S) +

PEEK (S) - PEEK (S)

- 6330 RETURN
- 6400 REM ** PRINTS DISPLAY INSTRUCTIONS
- 6401 REM ** FOR AXIS MOVEMENT **

GOSUB 5000 6415 V = 236450 RETURN 7000 REM ** PRINTS LABELS ** 7005 GOSUB 6000 7010 V = 21:H = 87020 GOSUB 5000 7025 RETURN 7200 REM *** PRINTS CLASS LABELS *** 7205 CL\$ = "1ST CLASS LEVER" 7210 IF X < 90 THEN CL\$ = "2ND CLASS LEVER" 7215 IF X > 165 THEN CL\$ = "3RD CLASS LEVER" 7223 INVERSE VTAB 23: HTAB 12: PRINT CL\$ 7225 7230 NORMAL 7250 RETURN REM PRINTS RA AND FA ***** 7300 7305 DRAW P AT X - 4,110 DRAW Q AT X + 4,1107310 RETURN 7350 7400 REM ** COMPARISON FOR LIMITS 7405 IF X > 180 THEN X = 180 7410 IF X < 70 THEN X = 707415 RETURN

6405 V = 21:H = 2:T\$ = "L=LEFT R=RIGHT C=CONTINUE":

- 7500 REM CLEARS LINE FOR 6800
- 7510 INVERSE : VTAB 23: HTAB 8: PRINT " "
- 7515 VTAB 23: HTAB 22: PRINT " "
- 7520 VTAB 23: HTAB 35: PRINT " "
- 7525 NORMAL
- 7530 RETURN
- 7700 REM ** DRAWS ARROW **
- 7705 ROT= 32
- 7710 IF PEEK (702) < > 0 THEN ROT= 0
- 7712 XDRAW 6 AT 180,80
- 7715 DRAW 6 AT 180,80
- 7720 ROT= 0
- 7725 RETURN
- 8000 REM **** DELAYS PRINTING
- 8005 FOR I = 1 TO T: NEXT
- 8050 RETURN
- 9000 REM *** WAITS FOR INPUT
- 9001 REM
- 9005 VTAB 24: HTAB 8
- 9010 FLASH
- 9012 POKE 16368,0
- 9015 GET KEY\$
- 9020 NORMAL
- 9050 RETURN
- 9100 REM ** FINDS RA & FA

9102 VTAB 22: HTAB 9: INVERSE : PRINT " ": VTAB 22: HTAB 3 O: PRINT " ": NORMAL 9105 RA = (ABS (X - 90)) / 5:FA = (ABS (160 - X)) / 5 9110 VTAB 22: HTAB 1: PRINT " FA = RA =.. 9112 RA\$ = STR\$ (RA): FA\$ = STR\$ (FA) 9114 INVERSE 9115 VTAB 22: HTAB 11 - LEN (FA\$): PRINT FA 9116 VTAB 22: HTAB 32 - LEN (RA\$): PRINT RA 9117 NORMAL 9120 RETURN 9200 REM ** CHECKS FOR CORRECT ANSWER 9205 IF FA = 12 THEN TEXT : HOME :V = 10:H = 1:TS = "EXCELLENT, YOU HAVE CHOSEN THE CORRECT": GOSUB 5000:V = 13:H = 6: T\$ = "AXIS PLACEMENT FOR BALANCE": GOSUB 5000: GOSUB 9000: P OKE 300,0: RETUR 9215 IF PEEK (300) = 1 THEN GOTO 9260 9218 POKE 300,1 9220 TEXT : HOME 9221 V = 10:H = 69222 IF FA > 12 THEN T\$ = "NO, YOU HAVE PLACED THE AXIS": G OSUB 5000:V = 13:H = 7:T\$ = "TOO FAR FROM THE FORCE": GOSUB 5000: GOSUB 9000: POKE 701,1: GOTO 9250 9228 TEXT : HOME 9230 T\$ = "NO, YOU HAVE PLACED THE AXIS": GOSUB 5000:V = 13:

H = 9:T = "TOO CLOSE TO THE FORCE": GOSUB 5000 9240 GOSUB 9000 9250 HOME :V = 10:H = 9:T\$ = "REMEMBER, FOR BALANCE,": GOSU B 5000 9252 V = 13:H = 13:T\$ = "F X FA = R X RA": GOSUB 5000 9254 V = 23:H = 15: INVERSE :T\$ = "TRY AGAIN": GOSUB 5000: N ORMAL 9256 GOSUB 9000: HOME : RETURN 9260 TEXT : HOME 9270 IF PEEK (701) = 1 THEN IF FA > 12 THEN V = 8:H = 7:T S = "AGAIN YOU HAVE PLACED THE": GOSUB 5000:V = 11:H = 4:T\$ = "AXIS TOO CLOSE TO THE RESISTANCE": GOSUB 5000: GOSUB 9000 : GOTO 9295 9280 IF FA > 12 THEN V = $10:H = 3:T^{\circ} = "THIS TIME YOU HAVE$ PLACED THE AXIS": GOSUB 5000:V = 13:H = 6:TS = "TOO CLOSE TOTHE RESISTANCE": GOSUB 5000: GOSUB 9000: GOTO 9295 9285 IF PEEK (701) = 0 THEN IF FA < 12 THEN V = 10:H = 5: T\$ = "YOUR AXIS PLACEMENT IS STILL TOO": GOSUB 5000:V = 13:H = 11:T\$ = "CLOSE TO THE FORCE": GOSUB 5000: GOSUB 9000: GOT 0 9295 9290 V = 10:H = 5:T\$ = "THIS TIME YOU HAVE PLACED THE": GOSU B 5000:V = 13:H = 6:T\$ = "AXIS TOO CLOSE TO THE FORCE": GOSU B 5000 9292 GOSUB 9000 9295 HOME : V = 10: H = 12: T\$ = "F X FA = R X RA": GOSUB 5000

9296 V = 13:H = 19:T\$ = "SO": GOSUB 5000 9297 V = 16:H = 12:T\$ = "12 X 10 = 60 X 2": GOSUB 5000 9298 GOSUB 9000: POKE 300,2 9300 REM ** BALANCE EXPLANATION 9301 REM ** AFTER 2 TRYS ***** 9302 HOME : V = 11:H = 4:TS = "FOR THE CORRECT AXIS PLACEMEN T": GOSUB 5000:V = 14:H = 11:T\$ = "LOOK AT THE FOLLOWING": G OSUB 5000: GOSUB 9000 9303 X = 1009305 GOSUB 6100: GOSUB 6200 9308 FLASH 9310 VTAB 23: HTAB 8: PRINT "120" 9311 VTAB 23: HTAB 29: PRINT "120" 9315 NORMAL 9320 FOR X = 94 TO 84 STEP - 2: DRAW 7 AT X,106: NEXT 9325 FOR X = 100 TO 155 STEP 2: DRAW 7 AT X,100: NEXT 9327 ROT= 16: DRAW 7 AT 160,100: DRAW 7 AT 85,106 9329 Y = 118: ROT = 09330 DRAW 9 AT 161, Y: DRAW 8 AT 155, Y: DRAW 10 AT 80, Y: DRA W 9 AT 86,Y 9340 VTAB 23: HTAB 34: GET KEY\$ 9345 TEXT 9350 RETURN 9400 REM ** GRAPHICS FOR SCISSORS REM ******************* 9401

9405 HGR : HCOLOR= 3: SCALE= 3: ROT= 64 9410 VTAB 22: HTAB 12: INVERSE : PRINT "FIRST CLASS LEVER" 9411 NORMAL 9412 VTAB 23: HTAB 8: PRINT "PRESS ANY KEY TO CONTINUE" 9415 DRAW 22 AT X,73: DRAW 23 AT X,74 9420 FOR I = 1 TO 500: NEXT 9425 XDRAW 22 AT X,73: XDRAW 23 AT X,74 9430 ROT= 72: DRAW 22 AT X,73: ROT= 56: DRAW 23 AT X,74 9435 FOR I = 1 TO 500: NEXT 9440 XDRAW 23 AT X,74: ROT= 72: XDRAW 22 AT X,73 9445 ROT= 54 9450 IF PEEK (- 16384) > 128 THEN POKE - 16368,0: RETUR N 9455 GOTO 9415 9460 RETURN 9500 REM ** GRAPHICS FOR 9502 REM ** WHEELBARROW 9505 HGR : HCOLOR= 3: SCALE= 2: ROT= R 9510 DRAW 19 AT X,Y 9515 DRAW 20 AT X2, Y2 9520 DRAW 21 AT X3,Y3 9525 VTAB 21: HTAB 11: INVERSE : PRINT "CHOOSE WHICH CLASS" : NORMAL 9530 VTAB 23: HTAB 5: PRINT " 1 = 1ST 2 = 2ND 3 = 3 RD ";

9550 RETURN

9700 REM ** CHECKS FOR ANSWER

9701 REM ***** VALIDITY *****

9705 IF ASC (ANS\$) > 48 THEN IF ASC (ANS\$) < 52 THEN ANS = ASC (ANS\$) - 48: RETURN

9710 POKE 705,1: VTAB 23: HTAB 4: PRINT "ENTER THE ";: INVE RSE : PRINT "NUMBER";: NORMAL : PRINT " OF YOUR CHOICE " 9715 FOR I = 1 TO 2000: NEXT

9750 RETURN

QUIZ PROGRAM - 10 QUESTIONS

9 REM ** SUBPROGRAM * * 10 REM ** BRANCH TO QUIZ * * 15 REM 20 SP = 25525 DIM T\$(40) 31 PRINT CHR\$ (4); "BLOAD NEWTAB, A2048" POKE 232,0: POKE 233,8: POKE 708,0: POKE 707,0 32 HOME : VTAB 12: HTAB 3: PRINT "PLEASE ENTER YOUR NAME "; 33 : INPUT NAME\$ 34 Z = 76835 RESTORE :L = 040 FOR C = 779 TO 789: POKE C,0 41 NEXT : C = 7781000 REM ** INTRODUCTORY PAGE ** 1005 HOME :V = 10:H = 9:T\$ = "LET'S SEE HOW WELL YOU": GOSU B 5000 1010 V = 13:T\$ = "UNDERSTAND THE CONCEPTS": GOSUB 5000 1015 V = 16:H = 14:T\$ = "OF LEVERAGE": GOSUB 5000: GOSUB 900 0 1100 REM *** QUESTION I ** 1102 RESTORE 1105 HOME : V = 6: H = 2: T\$ = "IF A LEVER HAS A FORCE ARM OF 5": GOSUB 5000

1110 V = $8:T^{\circ}$ = "CENTIMETERS AND A RESISTANCE ARM OF 10": GO SUB 5000 1115 V = 10:T\$ = "CENTIMETERS, WHAT IS THE MECHANICAL": GOSU B 5000 1120 V = 12:T\$ = "ADVANTAGE?": GOSUB 5000 1125 INVERSE 1130 V = 15:H = 9:T\$ = "1. 1/2": GOSUB 5000 1135 V = 17:T = "2. 2": GOSUB 5000 1140 V = 19:T = "3. 50": GOSUB 5000 1157 GOSUB 7500 1158 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1157 1160 GOSUB 7700 1200 REM ** QUESTION 2 ** 1205 HOME :V = 8:H = 2:T\$ = "THE FULCRUM (OR AXIS) IN A LEV ER": GOSUB 5000 1210 V = 10:T\$ = "SYSTEM IS THE POINT": GOSUB 5000 1215 INVERSE 1220 V = 13:H = 9:T\$ = "1. OF FORCE APPLICATION": GOSUB 5000 1225 V = 15:T\$ = "2. OF RESISTANCE": GOSUB 5000 1230 V = 17:T = "3. ABOUT WHICH THE LEVER": GOSUB 5000 1235 V = 18:H = 12:T\$ = "MOVES.": GOSUB 5000 1252 GOSUB 7500 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1252?' 1253 1255 GOSUB 7700 1260 TEXT

1300 REM ** QUESTION 3 ** 1305 HOME : V = 8:H = 2:T\$ = "IN WHICH CLASS OF LEVER DO THE FORCE": GOSUB 5000 1310 V = 10:T\$ = "AND RESISTANCE MOVE IN OPPOSITE": GOSUB 50 00 1315 V = 12:T\$ = "DIRECTIONS": GOSUB 5000 1320 GOSUB 7900 1332 GOSUB 7500 1333 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1332 1335 GOSUB 7700 1400 REM ** QUESTION 4 ** 1405 HOME : V = 9:H = 2:T\$ = "MOST EXAMPLES OF HUMAN LEVERS ARE:": GOSUB 5000 1410 GOSUB 7900 1416 GOSUB 7500 1417 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1416 GOSUB 7700 1420 1500 REM ** OUESTION 5 ** 1502 HOME 1505 V = 6:H = 2:T\$ = "THE EXACT POINT OF RESISTANCE OF A": GOSUB 5000 1510 V = 8:T\$ = "MOVING BODY SEGMENT IS:": GOSUB 5000?" 1512 INVERSE 1515 V = 11:H = 9:T\$ = "1. THE CENTER OF GRAVITY OF THE": GO SUB 5000

1520 V = 12:H = 12:T\$ = "SEGMENT.": GOSUB 5000 $1525 \text{ V} = 14:\text{H} = 9:\text{T}^{\circ} = "2.$ THE JOINT ABOUT WHICH THE": GOSUB 5000 1530 V = 15:H = 12:T\$ = "MOVEMENT IS OCCURING": GOSUB 5000 1535 V = 17:H = 9:T\$ = "3. THE CENTER OF GRAVITY OF THE": GO SUB 5000 1540 V = 18:H = 12:T\$ = "NON-MOVING BONE.": GOSUB 5000 1550 GOSUB 7500 1554 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1550 1555 GOSUB 7700 1600 REM ** OUESTION 6 *** 1602 HOME 1605 V = 4:H = 2:TS = "WHEN A MUSCLE MOVES A BONE,": GOSUB 5 000 1610 V = 6:T = "THE AXIS IS THE": GOSUB 5000 1616 INVERSE 1620 V = 9:H = 9:T\$ = "1. JOINT FORMED BY THE MOVING": GOSUB 5000 1625 V = 10:H = 12:T\$ = "BONE AND ANOTHER BONE.": GOSUB 5000 1630 V = 12:H = 9:T\$ = "2. MUSCLE ATTACHMENT ON THE": GOSUB 5000?' 1635 V = 13:H = 12:T\$ = "MOVING BONE.": GOSUB 5000 1640 V = 15:H = 9:T\$ = "3. MUSCLE ATTACHMENT ON THE": GOSUB 5000 1645 V = 16:H = 12:T\$ = "STATIONARY BONE.": GOSUB 5000

1660 VTAB V + 3: HTAB 9 1665 NORMAL 1670 GOSUB 7500 1675 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1670 1580 GOSUB 7700 1690 TEXT 1700 REM ** QUESTION 7 ** 1701 REM ************ 1705 TEXT : HOME :V = 4:H = 2:T\$ = "IF A 10 KILOGRAM WEIGHT IS 2 CM FROM": GOSUB 5000 1710 V = 6:TS = "THE AXIS, HOW FAR MUST A 5 KILOGRAM": GOSUB 5000 1715 V = 8:T\$ = "WEIGHT BE PLACED FROM THE AXIS FOR": GOSUB 5000 1720 V = 10:T\$ = "BALANCE?": GOSUB 5000 1725 V = 13:H = 9: INVERSE :T\$ = "1. 2 CM" 1726 GOSUB 5000 1730 V = 15:T = "2. 4 CM" 1731 GOSUB 5000 1735 V = 17:T\$ = "3. 5 CM": GOSUB 5000?' 1740 GOSUB 7500 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1740 1745 1748 GOSUB 7700 1800 REM ** QUESTION 8 **

1801 REM ************

1805 HOME :V = 8:H = 2:T\$ = "IN WHAT CLASS LEVER WILL THE": GOSUB 5000 1810 V = 10:T\$ = "RESISTANCE ARM ALWAYS BE SHORTER THAN": GO SUB 5000 1812 V = 12:T\$ = "THE FORCE ARM?": GOSUB 5000 1815 GOSUB 7900 1820 GOSUB 7500 1825 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1820 1830 GOSUB 7700 1900 REM ** QUESTION 9 ** 1901 REM ************ 1905 HOME : V = 9: H = 2: T = "A DOOR IS ALSO A LEVER. WHAT ": GOSUB 5000 1908 V = 11:T\$ = "CLASS IS IT?": GOSUB 5000 1910 GOSUB 7900 1915 GOSUB 7500 1920 IF PEEK (709) = 1 THEN POKE 709,0: GOTO 1915 GOSUB 7700 1925 2000 REM ** QUESTION 10 **?' REM ************** 2001 HOME : V = 9:H = 2:T\$ = "MOST SPORTS IMPLEMENTS ARE LEV 2005 ERS.": GOSUB 5000 2010 V = 11:T\$ = "WHAT CLASS ARE THEY USUALLY?": GOSUB 5000 2015 GOSUB 7900 2020 GOSUB 7500

2030 GOSUB 7700 3000 DATA 1,3,1,3,1,1,2,2,2,3 3505 HOME 3508 GOSUB 9100 3509 POKE Z,SCR 3510 VTAB 7: HTAB 8: PRINT "YOU MISSED ";: INVERSE : PRINT 10 - SCR;: NORMAL : PRINT " OF10 QUESTIONS." VTAB 10: HTAB 9: PRINT "NOW WOULD YOU LIKE TO:" 3515 3520 VTAB 13: HTAB 9: PRINT "1. TAKE THE QUIZ OVER" 3530 VTAB 16: HTAB 9: PRINT "2. REVIEW DEFINITIONS" 3540 VTAB 19: HTAB 9: PRINT "3. QUIT" 3545 V = 193550 GOSUB 7500 3552 GOSUB 9900 3555 ON ANS GOTO 3560,3570,3580 3560 HOME : GOTO 32 HOME : VTAB 12: HTAB 14: PRINT "PLEASE WAIT": PRINT 3570 HR\$ (4); "RUN RELOCATE" HOME 3580 4999 END REM **** THIS SUBROUTINE PRINTS 5000 REM **** LINES ONE AT A TIME **** 5001 5002 REM

IF PEEK (709) = 1 THEN POKE 709,0: GOTO 2020

5005 SPEED= 255

2025

5010 HTAB H 5015 FOR I = 1 TO LEN (T\$) 5017 VTAB V 5020 PRINT MID\$ (T\$,I,1); 5030 NEXT I 5050 RETURN 5100 REM RESPONSE TO INCORRECT 5101 REM ANSWER 5105 HOME : V = 8:H = 14:T\$ = "NO, REMEMBER": GOSUB 5000 5110 V = 11:H = 4:T\$ = "THE MECHANICAL ADVANTAGE IS = TO": G OSUB 5000 5115 V = 14:H = 8:T\$ = "THE FORCE ARM DIVIDED BY": GOSUB 500 0 5120 V = 17:H = 11:T\$ = "THE RESISTANCE ARM": GOSUB 5000: GO SUB 9000 5125 HOME :V = 11:H = 18:T\$ = "FA 5 1": GOSUB 5000 5130 V = 12:H = 12:T\$ = "MA = ---- = --- = -": GOSUB 5000?' 5135 V = 13:H = 18:T\$ = "RA 10 2": GOSUB 5000: GOSUB 9000 RETURN 5150 REM RESPONSE TO INCORRECT 5200 REM ANSWER 5201 HOME : V = 8:H = 3:T\$ = "NO, MOST DISTAL MUSCLE ATTACHM 5205 ENTS": GOSUB 5000 5210 V = 11:H = 10:TS = "ARE VERY CLOSE TO THE": GOSUB 5000

5215 V = 14:H = 11:T\$ = "BONE JOINT (AXIS).": GOSUB 5000: GO SUB 9000 5220 HOME :V = 8:H = 5:T\$ = "SO THE FORCE ARM IS QUITE SHOR T": GOSUB 5000 5225 V = 11:H = 16:T\$ = "COMPARED": GOSUB 5000 5230 V = 14:H = 9:T = "TO THE RESISTANCE ARM.": GOSUB 5000: GOSUB 9000 5235 GOSUB 8300 5240 TEXT 5250 RETURN 5300 REM RESPONSE TO INCORRECT 5301 REM ANSWER 5305 HOME : V = 7: H = 3: TS = "NO, THE FULCRUM IS THE STATION ARY": GOSUB 5000 5310 V = 10:H = 7:T\$ = "POINT ABOUT WHICH A LEVER": GOSUB 50 00?' 5315 V = 13:H = 10:T\$ = "CAN ROTATE. LOOK AT": GOSUB 5000 5320 V = 16:H = 9:T\$ = "THE FOLLOWING DIAGRAM:": GOSUB 5000: GOSUB 9000 5325 X = 13:M = 139:N = 79:HGR : HCOLOR = 35327 SCALE= 1: ROT= 0 5330 DRAW 5 AT M,N - 5: GOSUB 8100 5335 RETURN 5400 REM RESPONSE TO INCORRECT 5401 REM ANSWER
5405 HOME : V = 6:H = 4:T = "A FIRST CLASS LEVER IS THE ONL Y": GOSUB 5000 5410 V = 9:H = 8:T\$ = "KIND WHICH REOUIRES THAT": GOSUB 5000 5415 V = 12:T\$ = "THE FORCE BE OPPOSITE TO": GOSUB 5000 5420 V = 15:H = 7:T\$ = "THE DIRECTION OF MOVEMENT": GOSUB 50 00 5425 V = 18:H = 11:T\$ = "OF THE RESISTANCE.": GOSUB 5000 5430 GOSUB 9000 5435 X = 13:M = 139:N = 795437 GOSUB 8400 5440 TEXT 5450 RETURN REM ** QUESTION 5 5500 5505 HOME : V = 9:H = 3:TS = "NO, THE POINT OF RESISTANCE OF ANY": GOSUB 5000?' 5510 V = 12:H = 13:T\$ = "OBJECT IS IT'S": GOSUB 5000 5515 V = 15:H = 11:T\$ = "CENTER OF GRAVITY.": GOSUB 5000 5517 GOSUB 9000 5520 GOSUB 8500 5525 TEXT 5550 RETURN 5500 REM ** QUESTION 6 5603 M = 139:N = 795604 HOME :V = 10:H = 3:T\$ = "REMEMBER, AN AXIS IS A POINT ABOUT": GOSUB 5000

5605 V = 13:H = 9:T\$ = "WHICH A LEVER ROTATES.": GOSUB 5000: GOSUB 9000 5607 HOME 5608 V = 7:H = 4:T = "IF THE LEVER IS A BONE THEN THE": GOSUB 5000 5610 V = 10:H = 9:T\$ = "AXIS IS THE JOINT FORMED BY": GOSUB 5000 5615 V = 13:H = 12:T\$ = "THAT BONE AND THE ADJACENT": GOSUB 5000 $5620 \text{ V} = 16:\text{H} = 12:\text{T}^{\circ} = "\text{NONMOVING BONE."}: GOSUB 5000: GOSUB$ 9000 5650 GOSUB 8200 5660 RETURN 5700 REM ** INCORRECT ANSWER **?' 5701 REM ** QUESTION 7 ** 5704 HOME : VTAB 11: HTAB 13 5705 V = 11: PRINT "NO, FOR ";: INVERSE : PRINT "BALANCE": N ORMAL 5709 H = 135710 V = 14:T\$ = "R X RA = F X FA": GOSUB 5000: GOSUB 9000 5715 HOME :V = 8:T\$ = "WE KNOW THE FOLLOWING:":H = 9: GOSUB 5000 5720 V = 11:H = 6:T = "R = 10": GOSUB 5000 5722 V = 13:T = "RA = 2": GOSUB 5000 5725 V = 15:T = "F = 5": GOSUB 5000

5727 V = 17:T\$ = "FA = ?": GOSUB 5000 5730 GOSUB 9000 5735 V = 12:H = 20:T\$ = "2 X 10 = 5 X ?": GOSUB 5000 5737 V = 16:T = "20 = 5 X ?": GOSUB 5000 5740 VTAB 18: PRINT "? = ";: FLASH : PRINT "4": NORMAL 5745 GOSUB 9000 5750 HGR : HCOLOR= 3: SCALE= 1: ROT= 0 5751 DRAW 3 AT 166,71: DRAW 1 AT 103,68: DRAW 4 AT 154,64: DRAW 5 AT 122,66 DRAW 10 AT 99,108: DRAW 9 AT 108,108: DRAW 9 AT 156,91 5755 : DRAW 8 AT 144,91: DRAW 2 AT 87,65 5760 ROT= 32: DRAW 6 AT 184,50 5765 ROT= 16: DRAW 7 AT 184,86: DRAW 7 AT 122,86: DRAW 7 AT 122,106: DRAW 7 AT 89,106 5768 ROT= 0 5770 FOR X = 121 TO 179 STEP 2 5775 DRAW 7 AT X,92 5780 NEXT FOR X = 89 TO 117 STEP 2 5785 5788 DRAW 7 AT X,111: NEXT VTAB 21: HTAB 13: INVERSE : PRINT "LEVER BALANCES": NO 5790 RMAL VTAB 22: HTAB 12: PRINT "R X RA = F X FA" 5792 5793 VTAB 23: HTAB 11: PRINT "10 X 2 = 5 X 4" 5797 GOSUB 9000

5798 TEXT 5799 RETURN 5800 REM ** INCORRECT ANSWER ** 5801 REM ** QUESTION 8 ** 5805 HOME : V = 8:H = 5:T\$ = "WRONG! IF THE RESISTANCE ARM I S": GOSUB 5000 5810 VTAB 11: HTAB 3: INVERSE : PRINT "ALWAYS";: NORMAL : P RINT " SHORTER THAN THE FORCE ARM" 5815 V = 14:H = 1:TS = "THEN THE AXIS MUST BE ON ONE END AND ...": GOSUB 5000 5818 GOSUB 9000 5820 HOME :V = 8:H = 7:T\$ = "THE FORCE ON THE OTHER END.": GOSUB 5000 5825 V = 11:H = 2:T\$ = "SO THE RESISTANCE MUST BE BETWEEN" 5826 GOSUB 5000 5830 V = 14:H = 10:T\$ = "THE FORCE AND THE AXIS.": GOSUB 500 0 5832 V = 17:T\$ = "REMEMBER, THIS DEFINES A 2ND CLASS LEVER": H = 1: GOSUB 50005835 GOSUB 9000 5850 RETURN 5900 REM ** WRONG ANSWER ** 5905 REM ** QUESTION 9 ** 5910 HOME : V = 8:H = 1:T\$ = "MOST DOORS ARE SECOND CLASS LE VERS."

5911 GOSUB 5000 5915 V = 11:H = 7:T\$ = "THE AXIS IS AT THE HINGES;": GOSUB 5 000 5920 V = 14:H = 2:T\$ = "THE RESISTANCE IS THE DOOR'S CENTER" : GOSUB 5000 5925 V = 17:H = 1:T\$ = "OF GRAVITY AND THE FORCE IS AT THE K NOB": GOSUB 5000 5930 GOSUB 9000 5935 HGR : HCOLOR= 3: ROT= 0: SCALE= 3 5936 DRAW 24 AT 100,128 5937 SCALE= 1: DRAW 19 AT 113,82?' 5938 DRAW 8 AT 110,80 5939 DRAW 10 AT 133,81 5940 DRAW 5 AT 169,66 5941 DRAW 1 AT 148,57 5942 VTAB 23: HTAB 11: INVERSE : PRINT "SECOND CLASS LEVER" : NORMAL 5943 GOSUB 9000 5944 TEXT 5950 RETURN 6000 REM *** SETS LABEL WINDOW *** 6001 REM 6005 VTAB 21: HTAB 1 CALL - 958 5010 6050 RETURN

6100 REM ** WRONG ANSWER **

6101 REM ** QUESTION 10 **

6110 V = 11:T\$ = "(BATS, RACKETS, CLUBS, ETC.)":H = 6: GOSUB 5000

6115 V = 14:T\$ = "ARE 3RD CLASS LEVERS":H = 10: GOSUB 5000 6120 GOSUB 9000

6125 HOME :V = 4:T\$ = "ALTHOUGH SOMEWHAT MORE COMPLICATED": H = 3: GOSUB 5000?'

6130 V = 7:T\$ = "THAN OUR PREVIOUS EXAMPLES":H = 7: GOSUB 50 00

6135 V = 10:T\$ = "THE LEVER PARTS ARE LISTED BELOW":H = 4: G OSUB 5000

6140 V = 13:H = 1:T\$ = "1. AXIS IS AT THE MAJOR JOINT OF MOT ION": GOSUB 5000

6142 V = 16:T = "2. RESISTANCE IS THE OBJECT BEING STRUCK": H = 1: GOSUB 5000

6145 V = 21:T\$ = "GRIP THE HANDLE":H = 4: GOSUB 5000

6148 GOSUB 9000

6150 RETURN

6300 REM ** PRODUCES SOUND WHEN

6301 REM ** CLASS CHANGES **

6302 REM 6310 S = -163366315 SOUND = PEEK(S) - PEEK(S) + PEEK(S) - PEEK(S) +PEEK (S) - PEEK (S) 6330 RETURN 7500 REM CHECKS FOR RESPONSE VALIDITY 7502 NORMAL 7503 VTAB V + 3: HTAB 9: POKE - 16368,0: GET ANSS 7505 IF ASC (ANS\$) - 48 < 0 THEN GOTO 7510?' 7506 IF ASC (ANS\$) - 48 > 3 THEN GOTO 7510 7507 ANS = ASC (ANS) - 48: RETURN7510 VTAB 23: HTAB 1: PRINT "ENTER THE ";: INVERSE : PRINT "NUMBER ";: PRINT "OF YOUR CHOICE." 7511 NORMAL 7515 POKE 709,1 7520 RETURN 7600 REM **CHOOSE POSITIVE 7601 REM ** REINFORCEMENT ** 7602 POKE C,1 7605 N = INT (RND (6) * 5) + 17610 FOR I = 1 TO 5 7615 IF I = N THEN GOSUB 7650: RETURN 7620 NEXT 7625 RETURN REM ** PRAISE WORDS ** 7650

7655 R\$(1) = "RIGHT"7656 R\$(2) = "GOOD!"7657 R\$(3) = "YES, YOU'RE RIGHT" 7658 R(4) = "EXCELLENT"7659 R\$(5) = "YEP"7665 HOME : H = (40 - LEN (R\$(N))) / 27670 VTAB 12: HTAB H: PRINT R\$(N) 7675 T = 2000: GOSUB 8000?' 7677 SCR = SCR + 17680 RETURN 7700 REM ** READ CORRECT ANSWER ** FROM DATA STATEMENT 7701 REM 7702 ** AND COMPARES WITH REM 7703 REM ** INPUT ********* 7704 POKE Z, ANS: Z = Z + 1: C = C + 17705 READ M 7708 L = L + 1: REM QUESTION COUNTER IF ANS = M THEN GOSUB 7600: RETURN 7710 ON L GOSUB 5100,5300,5400,5200,5500,5600,5700,5800,590 7712 0,6100 7715 RETURN REM ** BLANKS ANS SPACE ** 7800 FOR J = V + 3 TO V + 97805 7810 FOR I = 9 TO 20

7815 VTAB J: HTAB I: PRINT " "

7820 NEXT J 7825 RETURN 7900 REM ** COMMON FOILS *** 7902 INVERSE 7905 VTAB V + 3: HTAB 9 7910 PRINT "1. 1ST CLASS"?' 7915 VTAB V + 5: HTAB 9: PRINT "2. 2ND CLASS" 7920 VTAB V + 7: HTAB 9: PRINT "3. 3RD CLASS" 7925 V = V + 77928 NORMAL 7930 RETURN 8000 REM **** DELAYS PRINTING 8005 FOR I = 1 TO T: NEXT 8050 RETURN 8100 REM ** MOVING LEVER ** 8105 R = 568108 ROT= R 8110 SCALE= 3 8117 GOSUB 6000 8118 V = 21:H = 7:T\$ = "LEVER ROTATES AROUND AXIS": INVERSE : GOSUB 5000: NORMAL 8119 V = 23:H = 5:T\$ = "M = MOVE LEVER C = CONTINUE": G OSUB 5000

7818 NEXT I

8120 ROT= R: DRAW X AT M,N

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8121 GOSUB 6300
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- 8125 GET KEYS: POKE 708,0
- 8126 IF KEY\$ = "C" THEN RETURN
- 8127 GOSUB 8900
- 8128 IF PEEK (708) = 1 THEN GOTO 8125
- 8130 XDRAW X AT M,N?'
- 8135 R = R + 4
- 8140 IF R > 72 THEN GOTO 8150
- 8145 GOTO 8120
- 8150 R = R 8: ROT= R: DRAW X AT M,N
- 8152 GOSUB 6300
- 8155 GET KEY\$
- 8158 IF KEY\$ = "C" THEN RETURN
- 8159 GOSUB 8900: IF PEEK (708) = 1 THEN GOTO 8155
- 8160 XDRAW X AT M,N
- 8165 R = R 4: IF R = 56 THEN GOTO 8120
- 8170 ROT= R: DRAW X AT M,N
- 8175 GOSUB 6300
- 8185 GOTO 8155
- 8188 SCALE= 1
- 8190 RETURN
- 8200 REM ** MOVING BONE **
- 8201 REM ** OUESTION 6 **
- 8205 HGR : HCOLOR= 3: SCALE= 1: ROT= 0

8206 R = 0

8210 DRAW 15 AT 100,100 8215 DRAW 17 AT 100,100 8220 DRAW 5 AT 97,98 8221 IF L < > 6 THEN RETURN 8222 GOSUB 8230?' 8223 R = 54: ROT = 648225 RETURN 8230 REM ** MOVING BONE ** 8231 REM ** PART II ** 8232 R = 64: ROT = 648234 GOSUB 6000 8236 HOME :V = 21:H = 5:T\$ = "M = MOVE BONE C = CONTI NUE": GOSUB 5000 8238 V = 23:H = 14:T\$ = "JOINT = AXIS": INVERSE : GOSUB 5000 : NORMAL 8239 M = 100:N = 1008240 GET KEY\$ 8242 IF KEYS = "C" THEN RETURN 8245 GOSUB 8900 8246 IF KEY\$ < > "M" THEN GOTO 8236 8250 XDRAW 17 AT M,N 8255 PEEK (707) = 1 THEN R = R - 8 ΙF IF PEEK (707) = 0 THEN R = R + 8 8256 IF R < 0 THEN R = 08258

8250 ROT= R

- 8265 DRAW 17 AT M,N
- 8270 IF R > 72 THEN POKE 707,1
- 8275 IF R = 56 THEN POKE 707,0
- 8276 ROT= R?'
- 8280 GOTO 8240
- 8282 GOSUB 9000
- 8285 RETURN
- 8300 REM ** GRAPHICS FOR Q4
- 8301 REM **************
- 8305 GOSUB 8200
- 8310 DRAW 18 AT 100,100
- 8315 SCALE= 2: DRAW 8 AT 114,119: SCALE= 1
- 8320 DRAW 2 AT 136,98
- 8325 GOSUB 6000
- 8330 HOME :V = 21:H = 12:T\$ = "THIRD CLASS LEVER"
- 8335 INVERSE : GOSUB 5000: NORMAL
- 8336 V = 23:H = 10:T\$ = "RA IS LONGER THAN FA": GOSUB 5000
- 8340 GOSUB 9000
- 8350 RETURN
- 8400 REM ** GRAPHICS FOR 03 **
- 8401 REM *******************
- 8405 HGR
- 8406 HCOLOR= 3
- 8407 SCALE= 1: ROT= 0
- 8410 DRAW 1 AT 105,70

- 8411 DRAW 2 AT 90,67
- 8412 DRAW 5 AT 139,71
- 8413 DRAW 6 AT 115,71?'
- 8420 ROT= 32: DRAW 6 AT 191,51: ROT= 0
- 8425 SCALE= 3
- 8430 DRAW 8 AT 174,67
- 8435 DRAW 13 AT 139,79
- 8440 GOSUB 6000

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8445 V = 21:H = 12:T$ = "FIRST CLASS LEVER": INVERSE : GOSUB
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5000: NORMAL

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8450 V = 23:H = 1:T$ = "FORCE MOVES DOWN. RESISTANCE MOVES
```

- UP.": GOSUB 5000
- 8455 GOSUB 9000
- 8460 RETURN
- 8500 REM ** GRAPHICS FOR Q5 **
- 8505 GOSUB 8200
- 8512 ROT= 32: DRAW 15 AT 142,89: ROT= 0
- 8513 DRAW 2 AT 130,98
- 8514 DRAW 18 AT 100,100

8515 GOSUB 6000

8518 V = 21:H = 12:T\$ = "THIRD CLASS LEVER": INVERSE : GOSUB 5000: NORMAL

8520 V = 23:H = 1:T\$ = "R = CENTER OF GRAVITY OF MOVING SEGM ENT": GOSUB 5000

8525 GOSUB 9000 8550 RETURN ?' 8900 REM CHECKS FOR ANSWER 8901 REM VALIDITY IF KEY\$ = "M" THEN RETURN 8905 8910 HOME : V = 21: H = 128915 TS = "ENTER ONLY 'M' OR 'C'" 8920 GOSUB 5000 8922 T = 2000: GOSUB 8000 8925 POKE 708,1 8950 RETURN 9000 REM *** WAITS FOR INPUT 9001 REM VTAB 24: HTAB 8 9005 9010 FLASH 9012 POKE - 16368,0 9015 GET KEYS 9020 NORMAL 9050 RETURN 9100 REM ** PRINTS BORDER ** REM **************** 9101 9105 INVERSE : FOR I = 2 TO 39: VTAB 2: HTAB I: PRINT " ": NEXT FOR I = 2 TO 23: VTAB I: HTAB 39: PRINT " ": NEXT 9110 9115 FOR I = 39 TO 2 STEP - 1: VTAB 23: HTAB I: PRINT " ":

NEXT ?'

9120 FOR I = 23 TO 2 STEP - 1: VTAB I: HTAB 2: PRINT " ": NEXT 9125 NORMAL 9130 RETURN 9900 REM ** FILE KEEPER ** 9901 REM ************** 9902 D = CHR\$ (4): PRINT D\$ 9905 D\$ = CHR\$ (4): PRINT D\$; "OPEN FILE" + NAME\$ 9910 PRINT D\$; "WRITE FILE" + NAME\$ 9912 PRINT NAMES 9913 C = 7799915 FOR Z = 768 TO 778 9920 PRINT PEEK (Z);: PRINT PEEK (C) 9921 C = C + 19922 NEXT 9925 PRINT D\$; "CLOSE FILE" + NAMES 9930 END 9935 RETURN

Appendix B

USER MANUAL FOR LEVER PROGRAM

DESCRIPTION

This program is designed to help students learn and apply the concepts of levers and leverage through a combination of text and graphics. The program should be beneficial to students from high school through university level. Specifically the student will:

- * Identify lever parts
- * Classify levers
- * Define lever terms
- * Perform lever calculations
- * Classify simple tools in terms of leverage

These objectives are on line in the program's introductory module.

There are three subprogram options that can be selected from the introduction program (INTRODUCTION). These subprograms along with respective program content appear below:

 Definitions - The interactive graphics for this module allow the user to repeatedly position the axis and note the change in lever classification. A bell rings each time classification changes. In subsequent screens, force arm and resistance arm are drawn and comparisons made for each type 84

of lever. Finally, the last screen allows the user to move the axis and note changes (provided in text at bottom of screen) in classification, lengths of resistance arm and arm, and mechanical advantage. Axis force placement is continually emphasized as the determining factor in lever classification. The defined following terms in subprogram are DEFINITIONS.

- * Lever components
- * Lever Classes
- * Force arm
- * Resistance arm
- * Mechanical advantage
- 2. Applications This module provides the user an opportunity to apply the $F \times FA = R \times RA$ formula to balance an object of known weight with a given The student moves the axis and notes force. resulting changes in force arm and resistance The figures required are formatted for easy arm. multiplication. The first incorrect answer will explanation and a chance to try again. bring an A second incorrect response will tell the student if he made the same error or a different one and will provide a detailed explanation followed by a

graphic showing correct axis placement along with formula substitutions. The user is then asked to classify serveral simple tools (wheelbarrow, scissors). Because of the relatively high probability of guessing the correct answer when there are only three choices, a graphic explanation follows correct and incorrect responses. Module content can be summarized as:

- * Balance
- * Tool classification
- 3. Quiz Ten questions from other modules' content are arranged according to anticipated degree of difficulty. Correct answers are rewarded with randomly selected words of positive reinforcement. Incorrect answers result in a an explanation (usually graphic) branch to followed by the next question. Upon completion, the student is provided a score which is sent to a "RECORDS" file that can be later read by the The student can branch from this instructor. point to the DEFINITIONS module or he can quit.

Requirements

The levers program was authored for an APPLE II plus (DOS 3.3) microcomputer with a minimum of 48K RAM. A single disk drive, CRT and high resolution graphic capabilities are also required. Color is not necessary.

OPERATION

For microcomputers that have automatic booting (turnkey system) the INTRODUCTION program will begin when the computer is powered on. Follow the steps below:

- Carefully place the disk in the disk drive and shut the door.
- 2. Turn on the CRT (television).
- 3. Turn on the APPLE II plus.
- If the program does not start automatically, type
 "PR#6" (without the quotes).
- If the program still does not start, see your computer expert.

The program is initiated with a graphic display of the title, author's name, program objectives and options for selections to enter any of the three subprograms (Definitions, Applications, or Quiz). The user may also choose to quit at this time.

The recommended order of subprogram presentation for learning purposes is:

- 1. Definitions
- 2. Applications
- 3. Quiz

The user also has the option of quitting after any program

execution.

Speed of screen presentation is controlled by the student. Unless otherwise stated, each suceeding screen will be called when the user presses any key. This can be done anytime after the curser starts to flash. Earlier responses will be ignored.

Disk Contents

There are 8 programs on your LEVER disk. All are locked to prevent accidental deletion or modification. Programs are:

- * Levers provides an introduction to the set of learning modules.
- * MOVEDEF Changes Apple's normal loading address for Definitions module.
- * MOVEAPP Changes Apple's normal loading address for Applications module.
- * MOVEQUIZ Changes Apple's normal loading address for Quiz module.
- * DEFINITIONS Learning Module
- * APPLICATIONS Learning Module
- * QUIZ Learning Module
- * NEWTAB Binary shape table for learning modules
- * BLEVERS Shape table for introductory program
 - In addition, each time the Quiz program is run, a file

with a record of student responses and score will be created. The instructor can read this information by running the RECORDS program. Follow the steps outlined below:

- 1. type "RUN RECORDS"
- 2. The program will ask for the name of the file you wish to read. All files will contain the word "FILE" followed immediately (without a space) by the student's name as entered prior to taking the quiz (i.e. FILEJUDY). If the user doesn't know the file name, he can press the RETURN key and a listing of disk programs will appear. Choose from only those files that do not have an "*" next to them. If the file name is spelled incorrectly, the program will ask you to enter it again.
- 3. Student name, question numbers, and student responses will then be displayed along with total number of correct responses. Incorrect answers will be followed by an "*".
- 4. Eventually these files will need to be deleted. Once they have been read there is usually no reason to keep them. If the instructor wishes to delete each file as it is read he presses "Y" when prompted by "Do you wish to delete file?"

(Y/N).

- 5. The program will then ask if there are more files to be read. If there are, it will begin the loop again.
- Upon program completion, all designated files will be deleted.

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